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model is shown in Table B-1

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= time to stop =

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$v_0/d_{brake} = (30 * 1.47) / 10 = 4.41 \text{ sec}$
 $X_c = v_{otr} + v_{ots} - (1/2)d_{brake}t^2 =$
 $(30 * 1.47 * 1.5) + (30 * 1.47 * 4.41) -$
 $(1/2)(10)(4.41)^2 = 163.39 \text{ ft}$ If the driver was any closer to the intersection than the X_c distance just

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$$s = \text{time to stop} = v_0 / d_{\text{brake}}$$
$$= (30 * 1.47) / 10 = 4.41 \text{ sec}$$
$$X_c = v_0 t_r + v_0 t_s - (1/2) d_{\text{brake}} t_s^2 =$$
$$(30 * 1.47 * 1.5) + (30 * 1.47 * 4.41) -$$
$$(1/2)(10)(4.41)^2 = 163.39 \text{ ft}$$

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