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5 TEIThe region that is common to both the Oboe circle and the Flute circle, but no other circle, as shown in the image below. This region, and only this region, must contain a star.

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When running multi-region simulations, it may be desirable to use different decomposition methods for one or more regions, or even to have fewer processors allocated to a particular region. If, for example, the multi-region simulation contains a large fluid region and a very small solid region, it can be advantageous to decompose the solid onto fewer processors.

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Figure 3: (a) The finite element model geometry, and (b) a sketch of the active region of the ball, where the contact surface and the transfer layer height are defined by polynomials $C(s, t)$ and $h(s, t)$, respectively. The polynomials $h(s, t)$ and $C(s, t)$ are interpo-lated from points calculated in MATLAB[®] based on wear calculations.

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