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Recurrent Neural Networks (RNNs) with Long Short-Term Memory units (LSTM) are widely used because they are expressive and are easy to train. Our interest lies in empirically evaluating the expressiveness and the learnability of LSTMs in the

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sequence-to-sequence
regime by training
them to evaluate
short computer
programs, a domain
that has traditionally
been seen as too
complex for neural ...

~~[1410.4615]~~

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We found it difficult
to train LSTMs to

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programs, so we used curriculum learning to simplify the learning problem. We design a curriculum procedure which outperforms both conventional training that uses no curriculum learning (baseline) as well as the naive curriculum learning of strategy of

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Bengio et al. (2009)
(Section 4).

~~LEARNING TO
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arXiv:2010.12621(cs)
[Submitted on 23 Oct
2020] Title: Learning
to Execute Programs
with Instruction
Pointer Attention
Graph Neural
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Authors: David Bieber,
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Charles Sutton, Hugo Larochelle, Daniel Tarlow. Download PDF. Abstract: Graph neural networks (GNNs) have emerged as a powerful tool for learning software engineering tasks including code completion, bug finding, and program repair.

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A significant effort has been made to train neural networks that replicate algorithmic reasoning, but they often fail to learn the abstract concepts underlying these algorithms. This is

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Evidenced by their
inability to generalize
to data distributions
that are outside of
their restricted
training sets, namely
larger inputs and
unseen data. We
study these
generalization issues
at the level of ...

~~Neural Execution
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arXiv:1410.4615v1
[cs.NE] 17 Oct 2014.
Learning to Execute
(Maddison &
Tarlow,2014) learned
a language model on
parse trees, and (Mou
et al.,2014) predicted
whether two
programs are
equivalent or not.
Both of these
approaches require

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Abstract

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This software allows
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(RNN) with Long-
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(LSTM) units on short
snippets of python
code. The Network is
trained to predict the
output of the
generated programs.
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Human perception of
3D shapes goes
beyond
reconstructing them
as a set of points or a~~

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geometric primitives:
we also effortlessly
understand higher-
level shape structure
such as the repetition
and reflective
symmetry of object
parts. In contrast,
recent advances in 3D
shape sensing focus
more on low-level
geometry but less on
these higher-level

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relationships. In this
paper, we ...

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Efficient movement
behaviour for
humanoid robots
from scratch is a hard
problem, as has been
illustrated by the
"Learning to run"
competition at NIPS
2017. The goal of this
competition was to
train a two-legged
model of a humanoid
body to run in a
simulated race course

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All submissions took
a tabula rasa
approach to
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learning (RL) and
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We seek to efficiently

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Transfer by Leveraging
shared structure
between different
tasks and
environments. For
example, cooking is
similar in different
kitchens, even though
the ingredients may
change location. In
principle, meta-
reinforcement
learning approaches
can exploit this

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shared structure, but
in practice, they fail
to adapt to new
environments when
adaptation requires
targeted exploration
...

~~[2008.02790]~~
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~~Adapting ...~~
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Effort has been made to train neural networks that replicate algorithmic reasoning, but they often fail to learn the abstract concepts underlying these algorithms. This is evidenced by their inability to generalize to data distributions that are outside of their restricted

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necessary to use
curriculum learning,
and while
conventional
curriculum learning
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(L2RPN) with an
emphasis on the
challenging use of
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flexibilities and the
safety robustness
requirement. The
L2RPN competition
which we will present
and analyze here,
takes some
inspiration from the
Learning to run [14]

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2017-LearningToRun:
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Recently we proposed
the Span Attribute
Tagging (SAT) Model

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Du et al. (2019) to infer clinical entities (e.g., symptoms) and their properties (e.g., duration). It tackles the challenge of large label space and limited training data using a hierarchical two-stage approach that identifies the span of interest in a tagging step and assigns labels to the

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span in a **Arxiv**
classification step.

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