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Vector: a quantity specified by a number (magnitude) and a direction (two numbers in three dimensions, e.g. two angles). This quantity transform specially under rotations. Examples: mass is a scalar, velocity is a vector. Example: A position vector is a vector bound to some origin and gives the position of some point P, say, relative to that ...

~~Vector Calculus { 2014/15~~

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A differential form is a linear transformation from the vector fields to the reals given by $\omega = \sum_{i=1}^n a_i dx_i$. (1.2) We identify a vector field v with the corresponding directional derivative $v = \sum_{i=1}^n v_i \frac{\partial}{\partial x_i}$. (1.3) The value of ω on the vector field v is $\omega \cdot v$

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$= \sum_{i=1}^n a_i v_i$. (1.4) If z is a scalar function on M , then it has a differential given by $dz = \sum_{i=1}^n \frac{\partial z}{\partial x_i} dx_i$.

~~Vector fields and differential forms~~

Vector calculus can be defined on other 3-dimensional real vector spaces if they have an inner product (or more generally a symmetric nondegenerate form) and an orientation; note that this is less data than an isomorphism to Euclidean space, as it does not require a set of coordinates (a frame of reference), which reflects the fact that vector calculus is invariant under rotations (the special ...

~~Vector calculus - Wikipedia~~

Linear Algebra and Calculus refresher Star. By Afshine Amidi and Shervine Amidi General notations ... dependence A set of vectors is said to be linearly dependent if one of the vectors in the set can be defined as a linear combination of the others. Remark: if no vector can be written this way, then the vectors are said to be linearly independent.

~~CS 229 - Linear Algebra and Calculus refresher~~

Linear Algebra for the Young Mathematician is a careful, thorough, and rigorous introduction to linear algebra. It adopts a conceptual point of view, focusing on the notions of vector spaces and linear transformations, and it takes pains to provide proofs that bring out the essential ideas of the subject.

~~Linear Algebra for the Young Mathematician~~

3 Linear independence, spanning and bases of vector spaces
3.1 Linear dependence and independence De nition. Let V be a vector space over the field K . The vectors v_1, v_2, \dots, v_n are said to be linearly dependent if there exist scalars $\lambda_1, \lambda_2, \dots, \lambda_n \in K$, not all zero, such that $\lambda_1 v_1 + \lambda_2 v_2 + \dots + \lambda_n v_n = 0$.

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10-2 Matrices and Linear Mappings of V_n into V_m 719. 10-3 Matrices as Linear Mappings 723. 10-4 Kernel, Range, Nullity, and Rank of a Matrix 724. 10-5 Identity Matrix, Scalar Matrix, Zero Matrix, Complex Matrices 727. 10-6 Linear Equations 730.

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But differentiation $\frac{d}{dx}$ is a linear operator (a fancy name for a linear map between function spaces) from the vector space of differentiable functions to the vector space of functions. This is important, but it's something else entirely, and not related to the "total derivative" and "Jacobian" etc that you were asking about. \endgroup – aes May 1 '15 at 4:42

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