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contains parts to build four different robots: A motion-activated robot that uses a passive infrared (PIR) sensor A light-tracking robot that uses photoresistors A line-following robot that uses infrared emitter-detectors An obstacle-avoiding robot that uses bump sensors However, in each Page 11/37

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high-interest, cutting-edge science and technology topics presented in an appealing format. Robotics offers a brief history of efforts to create machines that can perform functions in place of humans, then brings readers up-to-date on applications of robotic technology in exploration, industry, Page 16/37

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Bluetooth, has 3D modeled instructions that guide through each step of the building process. The app makes setup and uses extremely intuitive.

The robot senses the surroundings through the charge-coupled device (CCD) camera and sends to the receiver through the Radio Frequency (RF) wireless communication. We have already studied how to establish RF communication in RF Remote Control Circuit for Home Appliances Page 21/37

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tasks on a human level and adapt to changing conditions.

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known as free-flying robots, could soon assist humans in a variety of settings. However,...

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comes from the Czech word 'Robota'. that means 'Drudgery' or 'hard work' and 'forced labor'. 02 George Devol invented the first digital operated robot, 03 A robot is a machine that is designed to do tasks without the help of a person. 04 Robots only do what they are programmed.

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page (Fun Science Sheffield). Please email sheffield@fun-science.org.uk if you have any questions, or if you would like to be added to our WER mailing list and be the first to find out about the new clubs!

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