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Ugur HALICI - METU EEE - ANKARA 11/18/2004 EE543 - ANN - CHAPTER 2 6 CHAPTER II : Recurrent Neural Networks 2. 4. Gradient, Conservative and Dissipative Systems Level surfaces If we set $E(x)=c$, we obtain a family of surfaces known as level surfaces of E , as x takes on different values. On the assumption that E is single valued at each point, one and only one level surface passes through any given

~~CHAPTER II~~

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Ugur Halici In this paper, a scale and orientation invariant feature representation for 2.5 D objects is introduced, which may be used to classify, detect and recognize objects even under the ...

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Ugur HALICI - METU EEE - ANKARA 11/18/2004 EE543 - ANN - CHAPTER 4 2 CHAPTER IV : Combinatorial Optimization by Neural Networks 4.1. Combinatorial Optimization Problems The problems typically having a large but finite set of solutions among which we want to find the one that minimizes or maximizes a cost function are often referred

~~Combinatorial Optimization by Neural Networks~~

The solution space, denoted S , is the finite set of all possible solutions. The cost function, denoted by g , is a mapping from the set of solutions to real numbers, that is, $g: S \rightarrow \mathbb{R}$ [Aarts and Korst 89]. In the case of minimization, the problem is to find a solution $S^* \in S$, called globally-optimal solution, which satisfies $SgS \leq S^* = \min$

~~CHAPTER IV Combinatorial Optimization by Neural Networks~~

The output h_i of each hidden unit i is then computed by applying the basis function G to this distance $h_i = G(d_i, ?i)$ (9.1.2)

~~CHAPTER IX Radial Basis Function Networks~~

DESIGN, SETTING, AND PARTICIPANTS: Researcher challenge competition (CAMELYON16) to develop automated solutions for detecting lymph node metastases (November 2015–November 2016). A training data set of whole-slide images from 2 centers in the Netherlands with ($n = 110$) and without ($n = 160$) nodal metastases verified by immunohistochemical staining were provided to challenge participants to ...

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